



Module

Instruction Sheet

# High-speed Counter DVP-01HC

#### WARNING

- $\triangle$  Please carefully read this instruction thoroughly prior to use the DVP-01HC.
- $\triangle$  Make sure that power is OFF before wiring.
- A This is an OPEN TYPE PLC. The PLC should be kept in an enclosure away from airborne dust, humidity, electric shock risk and vibration. Also, it is equipped with protective methods such as some special tools or keys to open the enclosure, in order to prevent hazard to users or damage the PLC.
- △ Do NOT connect the AC main circuit power supply to any of the input/output terminals, or it may damage the PLC. Check all the wiring prior to power up.

#### 2

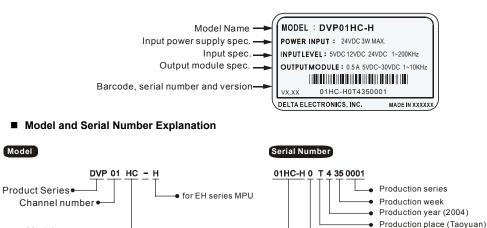
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#### INTRODUCTION

### 2.1 Model Name Explanation and Peripherals

- Thank you for choosing DELTA'S PLC DVP series. DVP-01HC high-speed counter input module could accept 200KHz pulse from external counter. It uses instruction FROM/TO to read/write the data in module via EH MPU. There are 33 Controlled Registers (CR, each register is 16-bit) in each module. 32 bits data consists of two continuous CRs and allow executing itself after setting CR.
- The different counter modes, such as single-phase mode, two phases mode, 16-bit mode or 32-bit mode, can be designated by CR. The controlled registers are written by instruction TO via MPU. When wiring, connect 24V, A24+, B24+, P24+, D24+, A12+, B12+, A5+, B5+, P5+ and D5+ to positive potential. In the same way, 0V, A24-, B24-, P24-, D24-, A12-, B12-, A5-, B5-, P5- and D5- should be connected to negative potential.
- Input signal source could be 1-phase or 2-phase encoder and voltage level could be 5V, 12V and 24V. Besides, it also provides two terminals, PRESET and DISABLE. When terminal "PRE" is on, the data in CR#10 and CR#11 will be sent to CR#20 and CR#21. That also means current value of counter will be changed to be factory setting. When terminal "DIS" is on, "count" operation is disabled.
- There are two outputs, YH0 and YH1, in hardware input module of DVP-01HC. When counter value is equal to the setting, the corresponding output point will activate. The transistors of output points are independent and isolated.

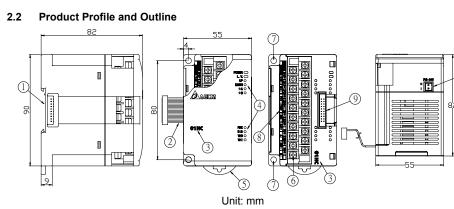
#### Nameplate Explanation



Serial number of version

Production Model

Model type • HC: High-speed counter module

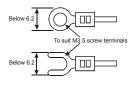


1. DIN rail track (35mm)	2. Mounting wire to connect extension module/extension unit
3. Model name	4. Status Indicator (Power, Run and ERROR)
5. DIN rail clip	6. Terminal
7. Mounting hole	8. Terminal layout
9. Extension port to connect extension module/unit	10. RS-485 communication port

#### LED Display

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1.	Power	: Power LED. When external +24V power is applied, it will be ON.
2.	L.V.	: Low voltage LED. When external power supply is lower than 19V, it will be ON.
3.	UP	: Count up LED
4.	DOWN	: Count down LED
5.	$\phi A$	: When input point A is ON, it will light.
6.	$\phi  B$	: When input point B is ON, it will light.
7.	PRE	: PRESET LED. When external terminal PRE is ON, it will light.
8.	DIS	: DISABLE LED. When external terminal DIS is ON, it will light.
9.	YH0, YH1	: When output points YH0 and YH1 are ON, it will light.



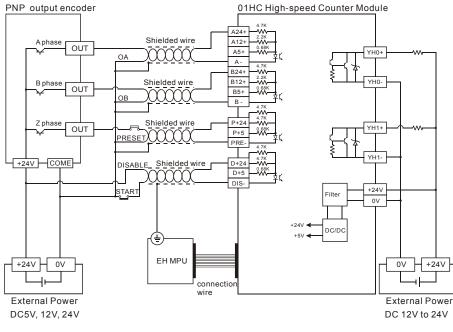


1. Please use O-type or Y-type terminals for I/O wiring terminals. The specification for the terminals is as shown on the left. Tighten PLC terminal screws to a torque of 5 to 8 kg-cm (4.3~6.9 in-lbs). 2. I/O signal wires or power supply should not run through the same

multi-wire cable or conduit.

3. Use copper conductor only, 60°C.

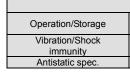
## External Wiring



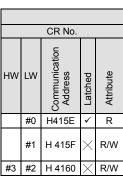
- A Make sure the positive/negative pole of 01HC input terminal wiring is correct when using NPN encoder
- ▲ Start-up current for 01HC is I<sub>PEAK</sub>=0.8A and general working current is I<sub>MAX</sub>=0.2A(input voltage is +24V).

3.1 Fund	tion Specifica					
Item						
Powe	er Supply					
	er of Connecting Jnits					
	Voltage Level					
	Max. Count Frequency					
Input Signal	Waveform					
	Count Mode					
Count Specification	Range					
	Comparison Method					
Output Signal	Output Form					
	Output to DVP-PLC					

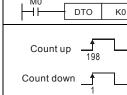
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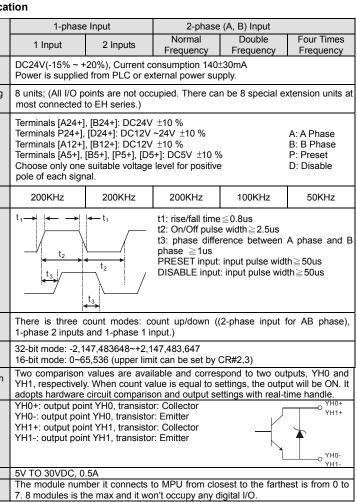






next count value will be 199. Setting notices 1 It must write with 32-bit

### FUNCTION SPECIFICATION



Environmental specifications

1. Operation: 0°C ~55°C (Temperature), 50~95% (Humidity), pollution degree 2
2. Storage: -25°C ~70°C (Temperature), 5~95% (Humidity)
Standard: IEC1131-2, IEC 68-2-6 (TEST Fc) / IEC1131-2 & IEC 68-2-27 (TEST
Ea)
All places between terminals and ground comply with the spec

#### CONTROLLED REGISTER (CR)

DVP-01HC High-speed Counter Module						
	Content	Setting Range				
	Model type	System used, read only, DVP-01HC model code=H'0120				
up/down mode 1-phase 1		Setting range: 0-1, factory setting K0				
		1-phase 1 input(Software): count up/down mode setting, count up: K0, count down:K1				
	Ring length	16-bit: factory setting is K65,536.				
	K2 K200	Write K200 into first extension module CR#2 and CR#3 (i.e. CR#3 = 0, CR #2 = 200). Setting range: K2 to K65,536.				
		When ring length is set to K200, The count value will be as shown on the left.				

Count up; when count value reaches 199, the

Count down: when count value reaches 0. the

next count value will be 0.

2. It only can be write-in when writing value is greater or equal to current count value.

3. It only can be set when counter stops counting and count mode is 16-bit.

	#4	H4	162	$\times$	R/W	in	struction	Instru	
	CR#	4		'0'(	(Off)		'1' (On)		
	b0		Cou	nt is	disab	ed	Count is enabl	ed	
	b1				utput i: abled	5	YH0 output is ena	abled	
	b2		YH1 output is disabled				YH1output is ena	abled	
	b3		YH0 and YH1 activate independently				YH0 and YH1 affect each other (they cannot be ON/OFF simultaneously)		
	b4		Pre	set	disable	ed	Preset is enab	led	
	b5~b	7				Re	eserved		
	b8		Not used				Clear error fla	ig	
	b9			Not	used		Clear YH0 output		
	b10			Not	used		Clear YH1 out	out	
	b11		_	Not	used		YH0 output set	ting	
	b12			Not	used		YH1 output set	ting	
b	13~b	15	Reserved						

ction, factory setting: K0

- 1. When b0 is set to 1 and terminal "DIS" is off, count is enabled. 2. When b1 is set to 1, YH0 (hardware comparison
- output) output is enable 3. When b2 is set to 1, YH1 (hardware comparison
- output) output is enabled. 4. When b3 is set to 1, YH0 and YH1 affect each
- other (they cannot be ON/OFF simultaneously). In other words, when YH0=ON, YH1 must be OFF and when YH0=OFF. YH1 must be ON. When b3=0. YH0 and YH1 activate independently
- 5. When b4=0, terminal "PRE" is disabled.
- 6. When b8=1, all error flags (CR#29) will be cleared 7. When b9=1, YH0 output will be cleared to be OFF.
- 8. When b10=1, YH1 output will be cleared to be OFF
- 9. When b11=1, YH0 output will be ON. 10.When b12=1, YH1 output will be ON.

Setting notes:

- After setting CR#4\_b8~b12 will be cleared to 0
- 2. It needs to set to disable count(b0=0) before setting count mode (CR#5).

		00/5	tting is K0	
	Count mode	CR#5 s		
		32 bits	16 bits	
2-phase 2 inputs	Normal frequency	K0	K1	
	Double frequency	K2	K3	
	Four times frequency	K4	K5	
1	-phase 2 inputs	K6	K7	
	Count mode	CR#5 s	settings	
		32 bits	16 bits	
1-phase 1 input	Count Up/Down is controlled by Hardware (Note 1)	К8	К9	
	Count Up/Down is controlled by software (Note 2)	K10	K11	
	lown control is controlled by exter lown control is controlled by interr			
	ode, the count values are all pos When overflow event is occurred	d, count value will	count lengt CR#3, #2	
	upper limit to 0 or from 0 to uppe 3 and CR #2.		upper limit	

Setting notes:

- It only can be written when count is disabled (bit 0 of CR#4 is 0).
- After writing, it will initial controlled registers as follows: CR#1: 0. CR#2, 3: 65,536. CR#10: 0. CR#12, 13: 32,767. CR#14, 15: 32,767. CR#20, 21: 0. CR#22, 23: 0. CR#24, 25: 0.

1-phase 1 input (K8~K11)		1-phase 2 inputs (K6~K7)
External input count up/down control (K8~K9)	Internal controlled register count up/down control	1-phase 2 inputs counter (K6, K7)
A input Off (count up) On (count down) Count up count down value	CR#1 K0 K1 A input count up count down value	A input
2-phase 2 inputs (K0~K5)		
Normal frequency (K0, K1)	Double frequency (K2, K3)	Four times frequency (K4, K5)
Ainput	Ainput	
B input 2 1 0	B input count value 0 1 2 3 4 3 2 1 0	B input

#6	~ #9				Reserved				
#11	#10	H4168	$\times$	R/W	Factory setting	Factory setting for counter (#10: Lower word / #11: Upper word), factory setting: K0 Setting notes: in 16-bit mode, CR#11 will be cleared to 0 when writing factory setting.			
#13	#12	H416A	$\times$	R/W	YH0 comparison value	YH0 output comparison value (#12: Lower word / #13: Upper word), factory setting: K32,767. Setting notes: in 16-bit mode, CR#13 will be cleared to 0 when writing YH0 comparison value.			
#15	#14	H416C	$\times$	R/W	YH1 comparison value	YH1 output comparison value (#14: Lower word / #15: Upper word), (factory setting: K32,767). Setting notes: in 16-bit mode, CR#15 will be cleared to 0 when writing YH1 comparison value.			

When current value of counter = comparison value, output current value YH0/YH1 will be ON and hold. User can clear output point by using b9 and b10 of CR#4.

If count value = comparison value by using PRESET or instruction TO, corresponding output YH0 or YH1 will be OFF. In other case that count value = comparison value does not use PRESET or instruction TO, corresponding output YH0 or YH1 will be ON.

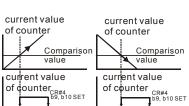
Reserved

counter

Current value of

#16~ #19

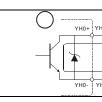
#21 #20 H4172 × R/W



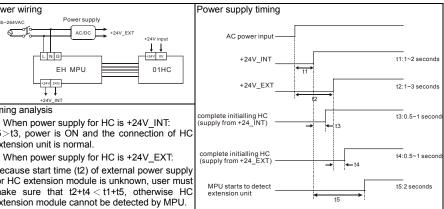
Current value of counter (#20: Lower word / #21: Upper word),

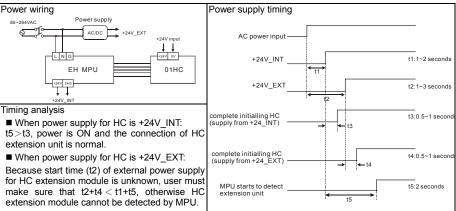
In 16-bit mode, value that is written must be less than ring

In 16-bit mode, CR#21 will be cleared to 0 when writing into



- damage internal circuit.
- as following





Troubleshooting

please check:

☆ "POWER" LED

- 🔆 L.V. LED

- 6 API FROM 78 D ♦ (m1): nu Instruction Explanation read. Writing sp Program write two Example X10 API то Ρ 79 D ♦ (m1): nu Instruction Explanatio wrote in Program Example X11

current value of counter Max. count value (#22: Lower word / #23: Upper word), factory #23 #22 H4174 R/W Max. count value setting is K0 Min. count value (#24: Lower word / #25: Upper word), factory #25 #24 H4176 R/W Min. count value setting is K0. #26 H4178 R Comparison result Comparison result CR#26 '0'(Off) '1'(On) CR#26 '0'(Off) '1'(On) Setting value ≦ Setting value > Setting value≤ Setting value > current b2 current value current value current value value Setting value = Setting value = Setting value ≠ Setting value = current b5 YH0 b1 current value current value current value value Setting value < current Setting value ≥ Setting value < Setting value  $\geq$ b0 b4 current value current value current value value #27 H4179 O R Action status The indication of count up/down and terminal status CR#27 '0'(Off) '1'(On) CR#27 '0'(Off) 1'(On) b0 b4 PRE input is Off PRE input is On Count up b1 Count down b5 DIS input is Off DIS input is On b2 A input is off A input is on b6 YH0 output is Off YH0 output is Or b3 B input is off b7 YH1 output is Off YH1 output is On B input is on that is used to save all error status. Refer to r Status FROM/TO exceeds the usage range exceeds upper limit(upper limit is CR#2 and #3 limit is 0 in ch as version 5, factory ,57600 bps, , even bit, ays 8Bit, ult value) b 4: 57600 bps(bit/sec.), b 5: 115200 bps(bit/sec.) b6~b14: reserved, b15: ASCII / RTU mode switch

factory setting is K0.

it must write with 32-bit.

Setting notes

length (CR#2).

- CR#0~CR#34: The corresponding addresses are H 415E-H 4180 for user to read/write by using RS-485.
- Baud rate could be 4800, 9600, 19200, 38400 and 57600bps. 1.
- Communication protocol can be Modbus ASCII mode and RTU mode. For ASCII mode, data 2. format is 7Bits, even, 1 stop bit (7 E 1). For RTU mode, data format is 8Bits, even, 1 stop bit (8 E 1).
- Function code: 03H: read register data. 06H: write one WORD data into register. 10H: write 3. multiple WORDs into register.

#### **TRIAL RUN & TROUBLESHOOTING**

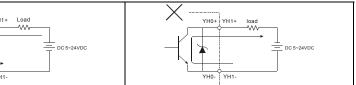
MPU connects to HC extension module

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- 1. Make sure that the power of MPU and extension unit is OFF before wiring.
- 2. Open extension port of EH MPU and connect to HC extension unit with cable. There is no connection order for EH MPU to connect extension unit, mix connection is allowed.
- 3. The power supply of HC extension unit must be external +24VDC power supply.
- 4. Before power up, check if the load circuit of output points YH0 and YH1 is correct, especially the circuit between YH0+, YH0- and YH1+, YH1-. There is a Zener Diode that is connected between YH0+, YH0- and YH1+, YH1- in HC. If the positive/negative pole is wrong, it may cause unexpected result.

			#29	H417B	$\times$	R/W	Error status	Data register the table below.		
		-								
٦	CR#29							Error		
	b0~ b3					Reserved				
			b4				CR number that is designated by instruction			
				b5				nen count-up value ex K2,147,483,647 in 32		
			<b>F</b> C				Overflow indication, When count-down value			

		05	in 16-	in 16-bit mode and it is K2,147,483,647 in 32-bit mode)						
		b6		Overflow indication, When count-down value is less than lower limit(lower li 16-bit mode and it is K-2,147,483,648 in 32-bit mode)						
	b7 <sup>.</sup>	~ b15	Rese	rved						
Γ	#30	H417C	() R	System version	Hexadecimal, display current software version, such 1.0A will be displayed as H'010A.					
	#31	H417D	0 R/W	, Communication address	RS-485 communication address, range set: 01~255, default value: K1					
	#32	H417E	0 R/M	, Baud Rate Setting	Baud rate setting: 4800,9600,19200bps,38400 bps,5 115200 bps. ASCII mode data format is always 7Bit, and 1 stop bit (7 E 1). RTU mode data format is alway even bit , and 1 stop bit (8 E 1) b0: 4800 bps(bit/sec.), b1: 9600 bps(bit/sec.) (default b2: 19200 bps(bit/sec.) b3: 38400 bps(bit/sec.)					



5. Before power up, check if A phase or B phase connects to correct voltage level. (there are three voltage level: +24, +12V and +5V) If +24V signal connects to +5V input terminal, it may

6. After power up MPU, it will start to detect extension module. If no external +24VDC power is applied to HC at this time or power is applied after EH MPU completing detecting extension module, the connection will fail. Therefore, power wiring and power supply timing should be

7. The maximum special extension modules number for EH MPU connects is 8 special extension modules. After power is ON, EH will save module codes of connected special modules in D1320~D1327 in order. The module code of 01HC is H'0120. It indicates communication is OK when H'0120 is displayed in the corresponding special D register by using HPP02 or other monitor software.

Judge the errors by the indicators on the front panel. When errors occurred on DVP PLC,

The "POWER" LED at the front of HC extension module will be lit (in green) if the power is on. If the indicator is not on when power up, please remove the wiring on terminals +24V. Once the indicator lights after this, it means that the 24V DC power supply of the PLC is overloaded. Please do not use the DC power supply from the +24V terminals, but use a DC24V power supply instead.

The "L.V." LED at the front of HC extension module will be lit if input voltage is not enough. The extension module won't active at this time.

RELATIVE INSTRUCTIONS							
(m1) (m2) (D) (n) Read Special Module CR Data							
umber of special module (m1=0~7). (m2): CR number of special module that will be D: address for saving reading data. (n): data number for reading once. pecial module #0 of CR#24 into D0 and special module #0 of CR#25 into D1. only data once (n=2).							
FROM K0 K24 D0 K2							
(m1) (m2) (S) (n) Special Module CR Data Write In							
number of special module (m1=0~7). $(m_2)$ : CR number of special module that will be n. $(s)$ : data to write in CR. $(n)$ : data number to write in once.							

◆ Using 32-bit instruction DTO to write D11 and D10 into special module#0 of CR#3 and CR#2. only write a data once (n=1).

_	DTO	K0	K2	D10	K1
---	-----	----	----	-----	----